

Formula Sheet

PHY111 – HS 2019

Physical constants

Gravitational constant	$G \approx 6.7 \times 10^{-11} \text{ Nm}^2\text{kg}^{-2}$
Free-fall acceleration	$g \approx 9.8 \text{ ms}^{-2}$
Speed of sound in air	$v_{air} \approx 340 \text{ m/s}$

Mathematics

$$\begin{aligned}\sqrt{2} &= 1.4 \\ \sqrt{1/2} &= 0.70 \\ \sqrt{3} &= 1.7 \\ \sqrt{1/3} &= 0.57 \\ \pi \text{ rad} &= 180^\circ\end{aligned}$$

Gravity

Gravitational force $|F| = \frac{GMm}{r^2}$
Gravitational force (on Earth's surface) $F = mg$
Gravitational potential energy (on Earth's surface)
 $U = mgh$

Mechanics

Linear motion, constant acceleration

$$\begin{aligned}x(t) &= x_0 + v_0t + \frac{1}{2}at^2 \\ v_f^2 &= v_0^2 + 2a\Delta x \\ v(t) &= v_0 + at \\ \text{Momentum } \mathbf{p} &= m\mathbf{v} \\ \sum \mathbf{F} &= m\mathbf{a} = \frac{\Delta \mathbf{p}}{\Delta t} \\ \text{Impulse } I &= \Delta p = \int F(t)dt \\ \text{Elastic force } F &= -kx \\ \text{Friction force } F &= \mu F_N \\ \text{Center of mass } \mathbf{R}_{cm} &= \frac{\sum_i m_i \mathbf{r}_i}{\sum_i m_i} \\ \text{Kinetic energy for linear motion } K &= \frac{1}{2}mv^2 \\ \text{Kinetic energy for a system of particles} \\ K &= \frac{1}{2} \sum_i m_i v_{cm}^2 + \sum_i \frac{1}{2} m_i v_{icm}^2 \\ \text{Work } W &= \int \mathbf{F} \cdot d\mathbf{x} = \Delta K \\ U &= -W \\ \text{Power } P &= \mathbf{F} \cdot \mathbf{v}\end{aligned}$$

Trigonometry

Trigonometry for common angles:

θ	$\sin \theta$	$\cos \theta$	$\tan \theta$
30°	$\frac{1}{2}$	$\frac{\sqrt{3}}{2}$	$\frac{\sqrt{3}}{3}$
45°	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{2}}{2}$	1
60°	$\frac{\sqrt{3}}{2}$	$\frac{1}{2}$	$\sqrt{3}$

Small angle approximations:

$$\begin{aligned}\sin x &\approx x \\ \tan x &\approx x \\ \cos x &\approx 1 - \frac{x^2}{2}\end{aligned}$$

Circular motion

$$\begin{aligned}\theta(t) &= \theta_0 + \omega_0t + \frac{1}{2}\alpha t^2 \\ \omega(t) &= \omega_0 + \alpha t \\ \text{Angular velocity } \omega &= 2\pi\nu = \frac{d\theta}{dt} = \frac{v}{r} = \frac{2\pi}{T} \\ \text{Tangential velocity } \mathbf{v} &= \boldsymbol{\omega} \times \mathbf{r} \\ \text{Centripetal acceleration } a_c &= \frac{v^2}{r} \\ \text{Angular momentum } \mathbf{L} &= \mathbf{r} \times \mathbf{p} = I\boldsymbol{\omega} \\ \text{Torque } \boldsymbol{\tau} &= \mathbf{r} \times \mathbf{F} \\ \sum \boldsymbol{\tau} &= I\boldsymbol{\alpha} = \frac{\Delta \mathbf{p}}{\Delta t} = \frac{d\mathbf{L}}{dt} \\ \text{Moment of inertia } I &= \int r^2 dm \\ \text{Huygens-Steiner (parallel axis) theorem } I &= I_{cm} + mr^2 \\ \text{Kinetic energy of a pure rotation } K &= \frac{1}{2}I\omega^2 \\ \text{Work for a pure rotation } W &= \int_{\theta_1}^{\theta_2} \tau d\theta \\ \text{Power } P &= \tau\omega \\ \text{Precession angular velocity } \omega_p &= \frac{rmg}{I\omega}\end{aligned}$$

Simple Harmonic Oscillator

Simple harmonic oscillator $\frac{d^2\mathbf{x}}{dt^2} = -\omega^2\mathbf{x}(t)$

Solution to the equation of motion $x(t) = A \cos(\omega t + \phi)$

Damping force $F = -bv$

Damped oscillations $m \frac{d^2x(t)}{dt^2} = -b \frac{dx(t)}{dt} - kx(t)$

Damped frequency $\omega' = \omega_0 \sqrt{1 - (\frac{b}{2m\omega_0})^2}$

Damping amplitude $A = A_0 e^{-\frac{b}{2m}t}$

Energy lost in a cycle $\frac{dE}{dt} = -\frac{b}{m}v^2$

Quality factor $Q = \frac{2\pi E}{|\Delta E|}$

Driving Force $F_{ext} = F_0 \cos(\omega t)$

For driven oscillations

Q-factor $Q = \frac{\omega_0}{\Delta\omega}$

Amplitude $A = F_0 / \sqrt{m^2(\omega_0^2 - \omega^2)^2 + b^2\omega^2}$

Phase $\tan \phi = b\omega / m(\omega_0^2 - \omega^2)$

Waves

Wave speed $v = \nu\lambda$

Wave equation $\frac{\partial^2 y}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 y}{\partial t^2}$

Speed of wave (for a string) $v = \sqrt{\frac{F}{\mu}}$

Harmonic wave $y(x, t) = A \sin(kx - \omega t)$

Wave number $k = \frac{2\pi}{\lambda}$

Energy density $\eta = \frac{E}{V}$

Intensity $I = \frac{\text{Power}}{A} = \eta v$

Doppler: source moving (u_s)

$f' = \frac{f_0}{1 \pm u_s/v}$, -: source approaching, +: source moving away

Doppler: receiver moving (u_r)

$f' = f_0(1 \pm \frac{u_r}{v})$, -: receiver moving away, +: receiver approaching

Standing waves $y(x, t) = A \cos(\omega t) \sin(kx)$

Interference

Constructive interference when $\Delta r = n\lambda$

Two-wave interference

$y_1 + y_2 = 2A \cos(\phi/2) \sin(kx - \omega t + \phi/2)$

Superimposition of standing waves

$y = \sum_n A_n \cos(\omega_n t + \phi_n) \sin(k_n x)$

Location of maxima for small angles $y = \frac{n\lambda D}{a}$

Combining two waves of different frequencies

$P_1 + P_2 = 2P_0 \cos(\pi \Delta f t) \sin(2\pi f_{av} t)$

Pseudo-Forces

In non-inertial reference frame $\mathbf{F}_p = -m\mathbf{a}$

Fluids

Pressure $P = \frac{F}{A}$

Bulk modulus $B = -\frac{P}{\Delta V/V}$

Continuity equation $I_v = Av = \text{constant}$

Bernoulli's equation $P + \rho gh + \frac{1}{2}\rho v^2 = \text{constant}$

Sound waves

Speed of sound $v = \sqrt{\frac{B}{\rho}}$

Displacement $S = S_0 \sin(kx - \omega t)$

Pressure change $P = P_0 \sin(kx - \omega t - \pi/2)$

with $P_0 = \rho\omega v S_0$

Intensity sound waves $I = \frac{1}{2} \frac{P_0^2}{\rho v}$

Sound intensity level $\beta = 10 \log(\frac{I}{I_0})$

Young's modulus $Y = \frac{F/A}{\Delta L/L}$

Speed of sound in solids $v_s = \sqrt{\frac{Y}{\rho}}$

Shear modulus $M_s = \frac{F_s/a}{\tan \theta}$